

Dear students,

I wanted to review some linear algebra for you, that we have been using. I especially want to do this with an eye towards the case of complex eigenvalues.

Recall that we have been trying to better understand the matrix exponential  $e^A$ . I said that this is particularly amenable to computation if  $A$  is *diagonalizable*; in this case, there is a matrix  $P$  such that  $A = PDP^{-1}$ , for some diagonal matrix  $D$ , and then we have

$$e^A = Pe^D P^{-1}.$$

The matrix  $P$  is a *change of basis matrix*, and I would like to review for you how to find it. I would also like to explain how this works in the case with complex eigenvalues, which is actually rather straightforward.

### Finding $P$

Recall that if  $A$  is diagonalizable, then there is a basis  $\{v_1, \dots, v_n\}$  of eigenvectors for  $A$ . The matrix  $P$  is the square matrix *whose columns are given by the  $v_i$* . The matrix  $P^{-1}$  is then just the inverse of this matrix. To briefly review how to find eigenvectors, we:

- (i) First, find the zeros of the characteristic polynomial  $\det(A - \lambda I) = 0$ .
- (ii) For each  $\lambda$  which is a zero, find  $\text{null}(A - \lambda I)$ ; any nonzero vector in this subspace is an eigenvector with eigenvalue  $\lambda$ .

(If there is considerable interest in another letter on finding eigenvectors, I can write one.) There are various ways to find the inverse of a given matrix. For two-by-two matrices, there is an explicit formula: the inverse of the matrix

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

is

$$\frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

For three-by-three matrices (or in fact  $n$ -by- $n$  matrices), an analogous formula exists. For brevity, I don't want to write it fully out here, but it's essentially the same as in the two-by-two case, except that one has to explicitly introduce the *adjugate* matrix  $\text{adj}(A)$ . That is, we have

$$A^{-1} = \frac{1}{\det(A)} \text{adj}(A).$$

To find the adjugate matrix, one forms the matrix of cofactors and then takes the transpose. This is a little tedious, but is well-explained, for example, on Wikipedia, under "adjugate matrix". (Again, I can write a letter if there is considerable interest.)

Actually, in practice, especially for larger matrices, there are other ways to find the inverse matrix that are almost surely preferable. I can't imagine I will make you compute anything greater than the three-by-three case, though, so the method I just sketched should be fine.

### The case of complex eigenvalues

Happily, the above methods work just as well for complex eigenvalues. One can literally do everything I said above, in the case where  $\lambda$  is complex. Note the following very important point, however: if  $A$  is a matrix with real entries,  $e^A$  will always have real entries, even if  $A$  has complex eigenvalues. This is apparent from the formula defining  $e^A$ . In practice, if you change basis as above, and you have complex eigenvalues, your final answer might *look* like it has imaginary parts to it; however, these will always cancel. To get them to cancel, it is very useful to use *Euler's identity*

$$e^{i\theta} = \cos(\theta) + i\sin(\theta) \tag{1}$$

which is a wonderful formula that comes up in all kinds of contexts.

### A worked example

Let's compute  $e^{tA}$ , where

$$A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

Since  $t$  is a scalar, the eigenvectors of  $A$  and  $tA$  are the same, and the corresponding eigenvalues of  $tA$  are just the eigenvalues of  $A$ , multiplied by  $t$ . The characteristic polynomial of  $A$  is

$$\lambda^2 + 1$$

which has roots  $\lambda = \pm i$ . To find an eigenvector with eigenvalue  $i$ , we look at  $\text{null}(A - iI)$ ; the vector  $(i, 1)$  is in this space. To find an eigenvector with eigenvalue  $-i$ , we look at  $\text{null}(A + iI)$ ; the vector  $(-i, 1)$  is in this space. Hence, we have

$$P = \begin{pmatrix} i & -i \\ 1 & 1 \end{pmatrix} \quad D = \begin{pmatrix} ti & 0 \\ 0 & -ti \end{pmatrix} \quad P^{-1} = \frac{1}{2i} \begin{pmatrix} 1 & i \\ -1 & i \end{pmatrix}$$

We have to compute  $Pe^D P^{-1}$ . We have

$$e^D = \begin{pmatrix} e^{it} & 0 \\ 0 & e^{-it} \end{pmatrix}.$$

We can now compute

$$Pe^D P^{-1} = \frac{1}{2i} \begin{pmatrix} i(e^{it} + e^{-it}) & e^{-it} - e^{it} \\ e^{it} - e^{-it} & i(e^{it} + e^{-it}) \end{pmatrix} = \begin{pmatrix} \cos(t) & -\sin(t) \\ \sin(t) & \cos(t) \end{pmatrix}.$$

The first equality in the previous line follows from multiplying out the three matrices. The second follows from Euler's Identity (1).

I'll remark that we could also have computed  $e^{tA}$  in this particular case by plugging in directly to the power series definition for the matrix exponential, and recognizing the power series for  $\cos(t)$  and  $\sin(t)$ . This is a good exercise for you to try, once you feel that you have mastered the above.